

# Controllability of Schrödinger equations and application to quantum rotors

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- 1: Controllability of finite-dimensional Schrödinger equations
- 2: Spectral conditions and resonant control
- 3: Controllability of  $\infty$ -dimensional Schrödinger equations



# Controllability of $\infty$ -dimensional Schrödinger equations

- 1 Small-time controllability of quantum rotors
- 2 Two theorems of Moser and Thurston
- 3 STC of phases
- 4 STC of flows

1 Small-time controllability of quantum rotors

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# Quantum rotors and BEC on $\mathbb{T}^d$

On  $\mathbb{T}^d = \mathbb{R}^d / \mathbb{Z}^d$ ,

$$i\partial_t \psi(t, x) = \left( -\Delta + V(x) + \sum_{j=1}^d (u_{2j-1}(t) \sin + u_{2j}(t) \cos) \langle b_j, x \rangle \right) \psi(t, x) + \kappa |\psi|^{2p} \psi,$$

where  $p \in \mathbb{N}$ ,  $\kappa \in \mathbb{R}$ ,  $V \in L^\infty(\mathbb{T}^d, \mathbb{R})$ , and

$$b_1 = (1, 0, \dots, 0), \quad \dots, \quad b_{d-1} = (0, \dots, 1, 0), \quad b_d = (1, \dots, 1).$$

It is locally-in-time well-posed<sup>1</sup>. We shall study small-time controllability, which is thus a well-defined notion if the time is small enough such that the equation is locally well-posed.

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In  $d = 1$ , it is just a rewriting of

$$i\partial_t\psi(t, x) = \left(-\Delta + V(x) + s(t) \cos(x + \varphi(t))\right)\psi(t, x) + \kappa|\psi|^{2p}\psi,$$

with  $u_1 = s \cos(\varphi)$ ,  $u_2 = -s \sin(\varphi)$ .

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# Notion of small-time approximate controllability

Introduce the  $L^2$ -unitary sphere

$$\mathcal{S} := \{\psi \in L^2(M, \mathbb{C}); \|\psi\|_{L^2(M)} = 1\}.$$

Denote by  $\psi(t; u, \psi_0)$  the solution:  $\psi_0 \in \mathcal{S} \Rightarrow \psi(t; u, \psi_0) \in \mathcal{S}$ , for all  $t \in \mathbb{R}$  such that the equation is well-defined, and for all  $u \in PWC$ .

## Definition 1 (STAC)

The equation is **small-time approximately controllable** (STAC) if, for every  $\psi_0, \psi_1 \in \mathcal{S}$  and  $\varepsilon > 0$ , there exist a time  $T \in [0, \varepsilon]$ , a global phase  $\theta \in [0, 2\pi)$  and a PWC control  $u : [0, T] \rightarrow \mathbb{R}^m$  such that

$$\|\psi(T; u, \psi_0) - e^{i\theta} \psi_1\|_{L^2} < \varepsilon.$$

# A recent controllability result

We shall prove the following result for simplicity in the linear case  $\kappa = 0$ , but it holds also in the nonlinear case<sup>2</sup>.

## Theorem<sup>3</sup>

The Schrödinger equation on  $\mathbb{T}^d$  is small-time approximately controllable.

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The Schrödinger equation on  $\mathbb{T}^d$  is small-time approximately controllable.

- The same methods apply also to equations with purely continuous spectrum, e.g.

$$i\partial_t\psi(x, t) = (-\Delta + u(t)e^{-x^2/2} + v(t)x)\psi(x, t), \quad x \in \mathbb{R}.$$

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- An open problem is to find a **scalar-input** Schrödinger equation on  $L^2(M)$  which is STAC<sup>4</sup>.

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## Definition 2 (STAR operators)

A unitary operator  $L$  on  $L^2(M, \mathbb{C})$  is STAR if, for every  $\psi_0 \in \mathcal{S}$  and  $\epsilon > 0$ , there exist  $T \in [0, \epsilon]$ ,  $\theta \in [0, 2\pi)$  and  $u \in PWC(0, T)$  such that  $\|\psi(T; u, \psi_0) - e^{i\theta} L\psi_0\|_{L^2} < \epsilon$ .

## Lemma 3

*The composition and the strong limit of STAR operators are STAR operators.*

# Some notions I

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*The composition and the strong limit of STAR operators are STAR operators.*

## Definition 4 (Unitary action of $\text{Diff}^0(M)$ on $L^2(M, \mathbb{C})$ )

For  $P \in \text{Diff}^0(M)$ , the unitary operator on  $L^2(M, \mathbb{C})$  associated with  $P$  is defined by

$$\mathcal{L}_P \psi = |J_P|^{1/2} (\psi \circ P),$$

where  $|J_P| = \det(DP)$  is the determinant of the Jacobian matrix of  $P$ . Then  $\|\mathcal{L}_P \psi\|_{L^2} = \|\psi\|_{L^2}$ .

# Some notions II

## Definition 5 (Flows $\phi_f^s$ )

For  $f \in \text{Vec}(M)$ ,  $\phi_f^s$  denotes the flow associated with  $f$  at time  $s$ : for every  $x_0 \in M$ ,  $x(s) = \phi_f^s(x_0)$  is the solution of the ODE

$$\dot{x}(s) = f(x(s)), \quad x(0) = x_0.$$

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## Definition 6 (STC notions)

- **STC of phases:** for every  $\varphi \in L^2(M, \mathbb{R})$ , the operator  $e^{i\varphi}$  is STAR,
- **STC of the group  $\text{Diff}_c^0(M)$ :** for every  $P \in \text{Diff}_c^0(M)$ , the operator  $\mathcal{L}_P$  is STAR.
- **STC of flows:** for every  $f \in \text{Vec}_c(M)$ , the operator  $\mathcal{L}_{\phi_f^1}$  is STAR.

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- **STC of flows:** for every  $f \in \text{Vec}_c(M)$ , the operator  $\mathcal{L}_{\phi_f^1}$  is STAR.

For  $f \in \text{Vec}(M)$  (resp.  $\text{Vec}_c(M)$ ) then  $\phi_f^1 \in \text{Diff}^0(M)$  (resp.  $\text{Diff}_c^0(M)$ ). Hence the following implication trivially holds

$$\text{STC of the group } \text{Diff}_c^0(M) \quad \Rightarrow \quad \text{STC of flows.}$$

# A Theorem of Moser<sup>5</sup>

**Transitivity** of the group action of  $\text{Diff}(M)$  on positive probability densities.

## Moser's Theorem

Let  $M$  be compact. Given  $\rho_0, \rho_1 \in C^\infty(M, (0, \infty))$ , there exists  $P \in \text{Diff}^0(M)$  s.t.

$$|J_P(x)|^{1/2} \rho_0(P(x)) = \rho_1(x)$$

iff

$$\int_M \rho_0^2 dx = \int_M \rho_1^2 dx.$$

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E.g. on  $\mathbb{T}$ : let  $\|\rho_0\|_{L^2} = \|\rho_1\|_{L^2} = C$ , and let  $\rho \equiv (2\pi)^{-1/2} C^{1/2}$ .

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$$\mathcal{L}_{P_j} \rho = \rho_j, \quad j = 0, 1$$

then  $P = P_2 P_1^{-1}$  is such that  $\mathcal{L}_P \rho_0 = \rho_1$ .

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then  $P = P_2 P_1^{-1}$  is such that  $\mathcal{L}_P \rho_0 = \rho_1$ . The  $P_j$  may be taken to be

$$P_j(x) = 2\pi C^{-1} \int_0^x \rho_j^2(y) dy, \quad j = 0, 1.$$

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# Reduction to the control of phases and diffeos

The first step consists in proving a certain **transitivity** property.

## Theorem

*STC of phases and the group  $\text{Diff}_c^0(M)$   $\Rightarrow$  STAC.*

This is a consequence of Moser's Theorem, applied to the radial part of the wavefunction's **polar decomposition**.

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By density, and since the solution operator is an isometry, WLOG

$$\psi_j = \rho_j e^{i\phi_j}, \quad \phi_j \in L^2(M, \mathbb{R}), \quad \rho_j \in C^\infty(M, (0, \infty)).$$

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Moser's Theorem implies the existence of  $P \in \text{Diff}_c^0(M)$  such that

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Then  $e^{i\phi_1} \mathcal{L}_P e^{-i\phi_0} \psi_0 = e^{i\phi_1} \mathcal{L}_P \rho_0 = e^{i\phi_1} \rho_1 = \psi_1$ . By Lemma 3, the operator  $e^{i\phi_1} \mathcal{L}_P e^{-i\phi_0}$  is STAR.

# A Theorem of Thurston<sup>6</sup>

## Definition of simple group

A subgroup  $H$  of a group  $G$  is said to be *normal* if, for any  $h \in H$  and  $g \in G$ ,  $ghg^{-1} \in H$ . A group  $G$  is said to be *simple* if its only normal subgroups are  $G$  and  $\{id\}$ .

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## Thurston's Theorem

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This gives a certain **surjectivity** property.

## Consequence: decomposition of diffeo as product of flows

Given  $P \in \text{Diff}_c^0(M)$  there exist  $n \in \mathbb{N}$  and  $f_1, \dots, f_n \in \text{Vec}_c(M)$  such that

$$P = \phi_{f_n}^1 \circ \dots \circ \phi_{f_1}^1.$$

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# Proof of the consequence

The subgroup

$$F(M) := \{\phi_{f_n}^1 \circ \cdots \circ \phi_{f_1}^1; n \in \mathbb{N}^*, f_1, \dots, f_n \in \text{Vec}_c(M)\}$$

is a normal subgroup of  $\text{Diff}_c^0(M)$ .

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is a normal subgroup of  $\text{Diff}_c^0(M)$ . Indeed, if  $X = \phi_{f_n}^1 \circ \dots \circ \phi_{f_1}^1 \in F(M)$  and  $P \in \text{Diff}_c^0(M)$  then  $PXP^{-1} = \phi_{g_n}^1 \circ \dots \circ \phi_{g_1}^1$  where  $g_j \in \text{Vec}_c(M)$  is the pushforward of  $f_j$  by  $P$

$$g_j(x) := (P \star f_j)(x) = DP(P^{-1}(x)) f_j(P^{-1}(x)),$$

thus  $PXP^{-1} \in F(M)$ .

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thus  $PXP^{-1} \in F(M)$ . By Thurston's Theorem,  $\text{Diff}_c^0(M) = F(M)$ .

# Reduction to the control of phases and flows

The second step consists in proving

## Theorem

*STC of flows*  $\Rightarrow$  *STC of the group*  $\text{Diff}_c^0(M)$ .

This is a simple application of the consequence of Thurston's Theorem.

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## Corollary

*STC of phases and flows*  $\Rightarrow$  *STAC*.

We are left to show the STAC of phases and flows for the Schrödinger equation on  $\mathbb{T}^d$ .

1 Small-time controllability of quantum rotors

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# STC of phases I

## Theorem<sup>7</sup>

The STC of phases holds for the Schrödinger equation on  $\mathbb{T}^d$ .

The main ingredients are:

- $$e^{-i\tau^{-1/2}W(x)} e^{i\tau(\Delta-V(x))} e^{i\tau^{-1/2}W(x)} \psi_0 \xrightarrow{\tau \rightarrow 0} e^{-i|\nabla W|^2} \psi_0.$$

Which follows from

$$e^{-i\tau^{-1/2}W(x)} e^{i\tau(\Delta-V(x))} e^{i\tau^{-1/2}W(x)} \psi_0 = \exp\left(i\tau(\Delta - V) + \tau^{1/2}\mathcal{T}_f - i|\nabla W|^2\right)$$

where  $f = \nabla W$ ,  $\mathcal{T}_f = \langle f, \nabla \cdot \rangle + \frac{1}{2} \operatorname{div}(f)$ . It is an explicit sequence of delta kicks.

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- And the density of a certain ***infinite-dimensional Lie algebra***.

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# STC of phases II

We next introduce  $\mathcal{H}_0 = \text{span}\{V_1, \dots, V_{2d+1}\}$  and  $\mathcal{H}_j$  the largest vector space whose elements can be written as

$$\phi_0 - \sum_{i=1}^N |\nabla \phi_i|^2, \quad \phi_i \in \mathcal{H}_{j-1}, \quad N \in \mathbb{N}.$$

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Then, we have that  $\cup_{j=0}^{\infty} \mathcal{H}_j$  is **dense** in  $L^2(\mathbb{T}^d, \mathbb{R})$ . The idea is that

$$2|\cos'(x)|^2 = 2\sin^2(x) = 1 - \cos(2x) \cong -\cos(2x),$$

and

$$2|\sin'(x)|^2 = 2\cos^2(x) = 1 + \cos(2x) \cong +\cos(2x).$$

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2 Two theorems of Moser and Thurston

3 STC of phases

4 STC of flows

# Strategy to show STC of flows

We next show the following.

## Theorem

*The STC of flows holds for the Schrödinger equations on  $\mathbb{T}^d$ .*

In view of the previous slides, the latter Theorem implies the main theorem, i.e. the STAC of the Schrödinger equations on  $\mathbb{T}^d$ .

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Our strategy to prove it is:

STC of phases  $\Rightarrow$  STC of flows of gradient vector fields  $\Rightarrow$  STC of flows.



Introduce the space of gradient vector fields on  $\mathbb{T}^d$

$$\mathfrak{G} = \{\nabla\varphi; \varphi \in C^\infty(\mathbb{T}^d, \mathbb{R})\} \subset \text{Vec}(\mathbb{T}^d).$$

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## Theorem

*Let  $f = \nabla\varphi \in \mathfrak{G}$  and  $P := \phi_f^1$ . Then  $\mathcal{L}_P$  is STAR for the Schrödinger equations on  $\mathbb{T}^d$  and  $\mathbb{R}^d$ .*

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## Theorem

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The first remark is that, being  $\mathcal{L}_P$  unitary, it must be the exponential of some skew-adjoint operator (**Stone Theorem**). We have

$$(\mathcal{L}_{\phi_f^t}\psi)(x) = \psi(\phi_f^t(x))e^{\frac{1}{2}\int_0^t \text{div}f(\phi_f^s(x))ds} = (e^{t\mathcal{T}_f}\psi)(x)$$

where  $\mathcal{T}_f = \langle f, \nabla \cdot \rangle + \frac{1}{2}\text{div}(f)$  is a skew-adjoint operator. In the first equality we used Liouville formula, and in the second equality the method of characteristics.

The proof then consists in showing the following strong convergences:

$$\left( e^{\frac{1}{n} \frac{i|\nabla\varphi|^2}{4\tau}} \underbrace{e^{\frac{i\varphi}{2\tau}} e^{\frac{i\tau}{n}(\Delta-V)} e^{-\frac{i\varphi}{2\tau}}}_{\exp \frac{1}{n} \left( i\tau(\Delta-V) + \mathcal{T}_f - \frac{i|\nabla\varphi|^2}{4\tau} \right)} \right) \xrightarrow{n \rightarrow \infty} e^{i\tau(\Delta-V) + \mathcal{T}_f} \xrightarrow{\tau \rightarrow 0} e^{\mathcal{T}_f} = \mathcal{L}_P$$

where  $\mathcal{T}_f = \langle f, \nabla \cdot \rangle + \frac{1}{2} \operatorname{div}(f)$ . In the first convergence we used Trotter-Kato product formula  $\lim_{n \rightarrow \infty} (e^{\frac{A}{n}} e^{\frac{B}{n}})^n = e^{A+B}$ .

## Theorem

$\mathfrak{L} := \{f \in \text{Vec}(M); \forall t \in \mathbb{R}, \mathcal{L}_{\phi_f^t} \text{ is } L^2\text{-STAR}\}$  is a Lie subalgebra of  $\text{Vec}(M)$ . Hence, by the previous Theorem,  $\text{Lie}(\mathfrak{G}) \subset \mathfrak{L}$ .

We show that if  $f, g \in \mathfrak{L}$  and  $P := \phi_{[f,g]}^1$  then  $\mathcal{L}_P$  is the strong limit of STAR operators.

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We show that if  $f, g \in \mathfrak{L}$  and  $P := \phi_{[f,g]}^1$  then  $\mathcal{L}_P$  is the strong limit of STAR operators. We use the following convergences

$$\left( e^{\frac{-1}{tn} \mathcal{T}_f} e^{-t \mathcal{T}_g} e^{\frac{1}{tn} \mathcal{T}_f} e^{t \mathcal{T}_g} \right)^n \xrightarrow{n \rightarrow \infty} \exp \left( \frac{-1}{t} \mathcal{T}_f + e^{-t \mathcal{T}_g} \frac{1}{t} \mathcal{T}_f e^{t \mathcal{T}_g} \right) \xrightarrow{t \rightarrow 0} e^{\mathcal{T}_{[f,g]}} = \mathcal{L}_P.$$

Do you remember the finite-dimensional analogue?

The last step of our strategy is proving that  $\text{Lie}(\mathfrak{G})$  is dense in  $\text{Vec}(\mathbb{T}^d)$ .

### Theorem

*For every  $f \in \text{Vec}(\mathbb{T}^d)$ , there exists  $(f_n)_{n \in \mathbb{N}} \subset \text{Lie}(\mathfrak{G})$  such that  $\mathcal{L}_{\phi_f^1}$  is the strong limit of  $(\mathcal{L}_{\phi_{f_n}^1})_{n \in \mathbb{N}}$ .*

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### Theorem

*For every  $f \in \text{Vec}(\mathbb{T}^d)$ , there exists  $(f_n)_{n \in \mathbb{N}} \subset \text{Lie}(\mathfrak{G})$  such that  $\mathcal{L}_{\phi_f^1}$  is the strong limit of  $(\mathcal{L}_{\phi_{f_n}^1})_{n \in \mathbb{N}}$ .*

The basic idea is that the Lie bracket of gradient vector fields is not a gradient vector field. E.g.,

$$[\nabla \cos(x_j), \nabla \sin(x_j)] = [\cos(x_j) \partial_{x_j}, \sin(x_j) \partial_{x_j}] = \partial_{x_j},$$

and

$$-\frac{1}{2}[\nabla \sin(x_j) \sin(x_k), \nabla \cos(x_k)] + \frac{1}{2}[\nabla \sin(x_j) \cos(x_k), \nabla \sin(x_k)] = \sin(x_j) \partial_{x_k}.$$



*Thanks for your attention!*